EZBackUp Team 20

Justin Charles, Justin Lam, Zhiyang Jin, Exiang Zhou, Austin Carroll

University of Massachusetts Amherst BE REVOLUTIONARY

Department of Electrical and Computer Engineering

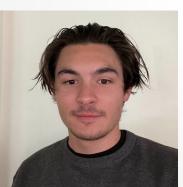
Meet our Team



Christopher V. Hollot Faculty Advisor



Justin Charles Computer Engineer



Austin Carroll Mechanical Engineer



Zhiyang Jin

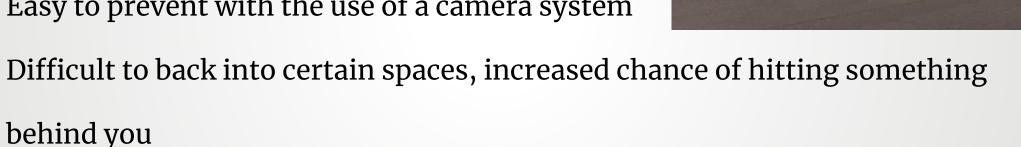


Exiang Zhou Computer Engineer



Background

- Over **50,000** accidents a year are related to towing
- **800,000**+ blind spot accidents occur each year
- Easy to prevent with the use of a camera system





Problem Statement

Driving is a task that many Americans undertake daily, it is a necessary function of human life today and will continue to be prevalent into the future. While this may be true, there will always be a need for added safety.



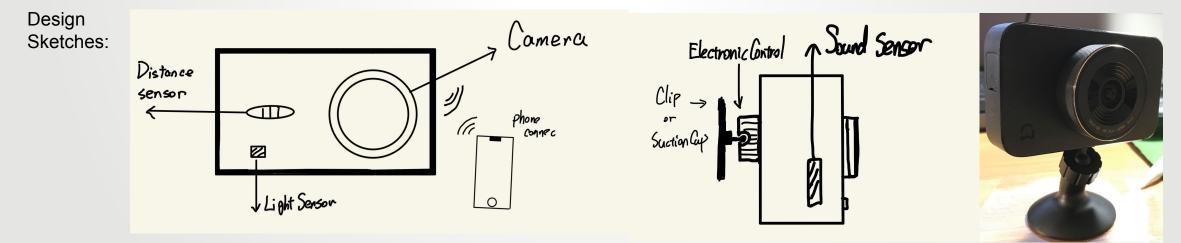






Project Goal

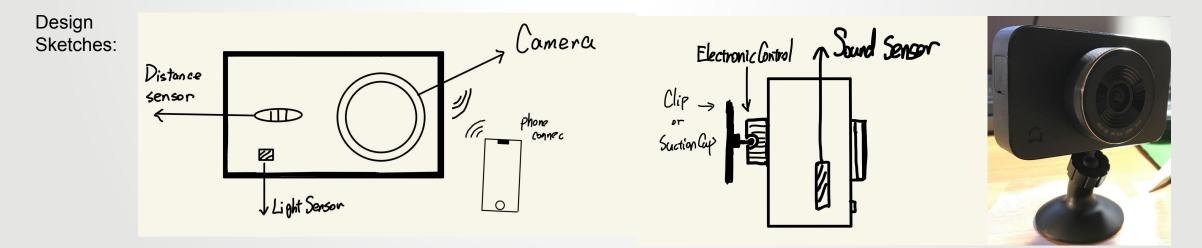
Problem: Driving is a task that many Americans undertake daily, it is a necessary function of human life today and will continue to be prevalent into the future. While this may be true, there will always be a need for added safety. Goal: We aim to create a backup camera system that is easy and accessible to install and use, while also being convenient and adding safety for the users driving experience.





Project Goal

We aim to create a backup camera system that is easy and accessible to install and use, while also being convenient and adding safety for the users driving experience.





Project Goal

Adapted for:

- Tow Cars (boats, cars, campers, etc.)
- UHAUL, Rented Vehicles

Functionality:

- Multiple Views
- Proximity Sensing
- Easily Mounted/Dismounted
- Wirelessly connected to Phone App



Specifications and Testing - Qualitative

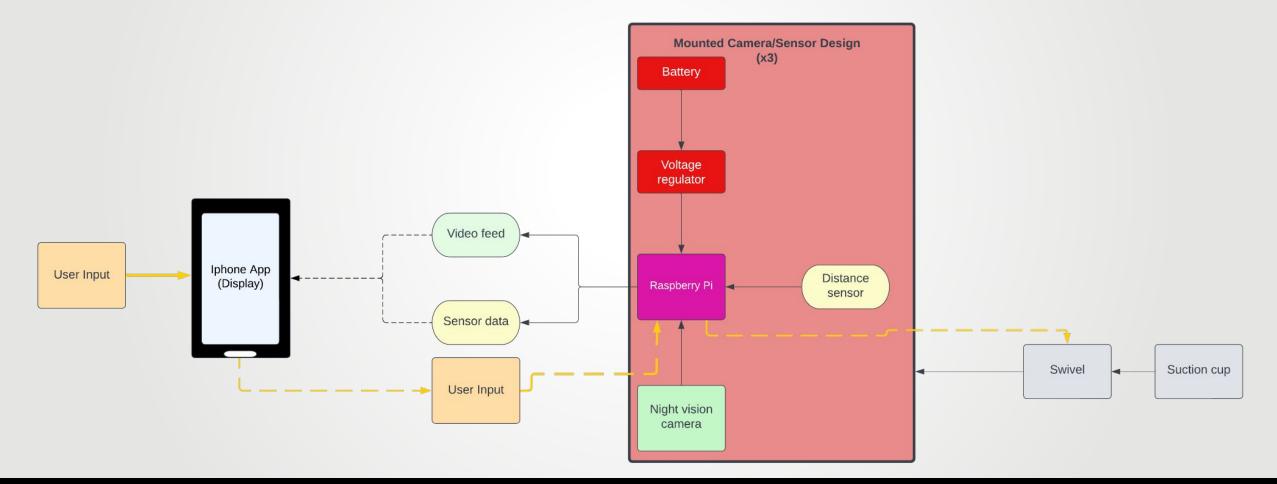
| System Specification | Test Plan |
|--|--|
| System will use up to 3 video systems wirelessly connected to smartphone | Inspect that up to 3 video feeds/sensors/motors will work on display |
| System display will show up to 3 video feeds, one feed may be chosen at a time | Inspect app to check that video feeds can be viewed and changed by user |
| System will provide distance and audio to the user via smartphone | Inspect app to check that distance and audio is output |
| Camera will have night vision capabilities | Inspect video feed at night and check that objects are visible |
| Camera Systems will be self powered | inspect that the system will work being self powered |
| Camera/Sensor system will be mountable and dismountable to vehicle | Mount system on vehicle and test by driving |
| System will be easy to set up | Survey 10 people with setup, ask to rate on a scale of 1-10 complexity of set up. <3 should be chosen. |

Specifications and Testing - Quantitative

| System Specification | Test Plan |
|--|--|
| System will give a slow audio alert when ≤2ft and an increasingly faster alert when ≤1ft | Get distance using sensors, manually measure distance |
| System cameras will rotate in intervals of 30 degrees on a horizontal axis | Measure angle change when given rotation input for cameras |
| Individual camera systems will have power for up to 3 months at a time without replacement | measure change in power over a day to estimate power loss |



Hardware Block Diagram



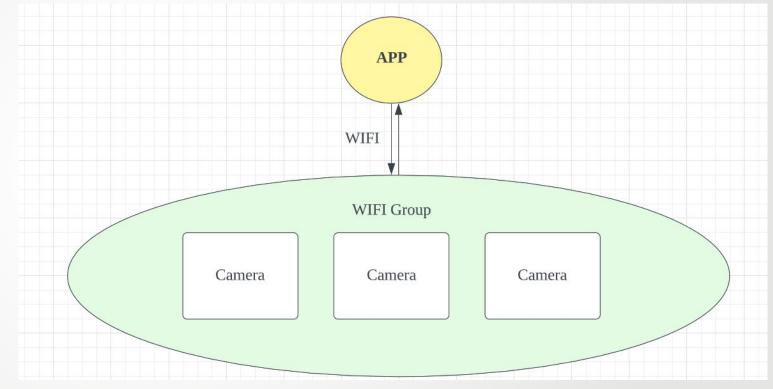


Wirelessly Data Transfer

WIFI Direct

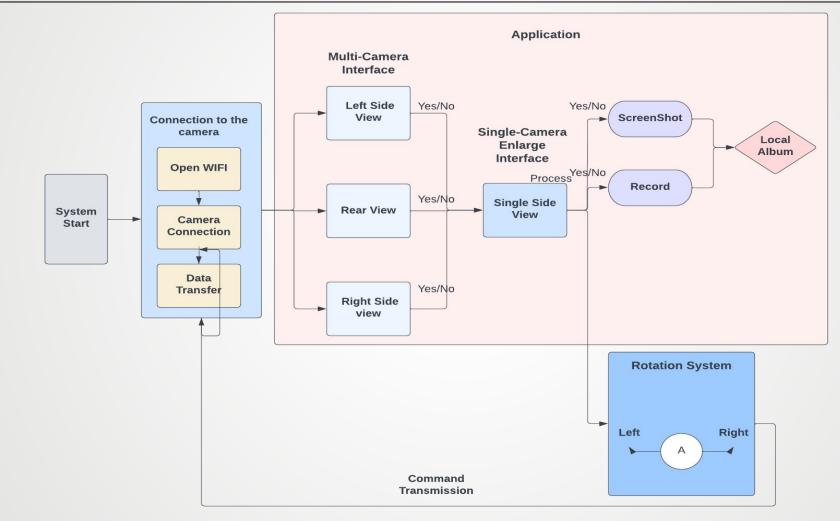
WiFi Direct is built upon the same WiFi technology used by most modern consumer electronic devices to communicate with wireless routers.

Transmission speed is 100 times faster than Bluetooth



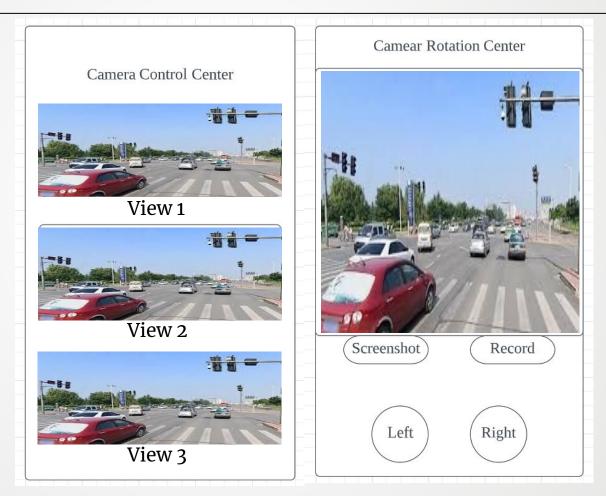


Software Diagram





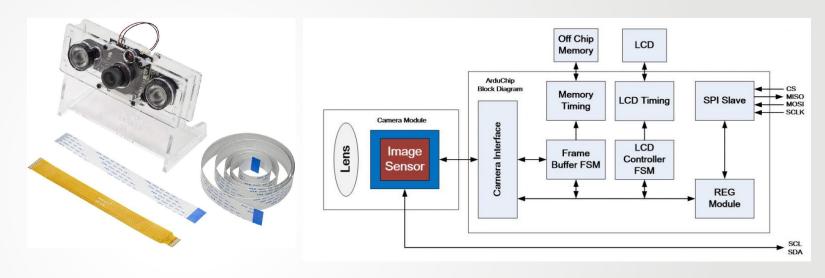
Software Design Sketch





Camera

- Arducam
 - Angle of view: 100 degree
 (D) x 80 degree (H)
 - High frame rates: 30fps@1080P - 90fps@480p
 - Max Resolution: 2592*1944
- Night Vision
 - Camera will have night vision functionality
 - Built in automatic IR cut switch



IR-CUT Switch Automatically



IR Sensitivity During the Night



Visible Light During the Daylight



Distance Sensor

- HC-SR04
 - Sensor to detect distance between vehicle and other objects



| Supply voltage | 1.7V to 3.6V |
|-------------------|----------------------|
| Measurement Range | 0.8 inches to 15feet |
| Current Drain | 0.65µA |
| Output Data Rates | 100ms |



Motor and Mounting System

Motor

 Adafruit NFMA-17 12V 350 mA Stepper Motor



Mounting System

- CONBOLA Heavy Duty Suction Cups
- 3-D Printed Camera Mount

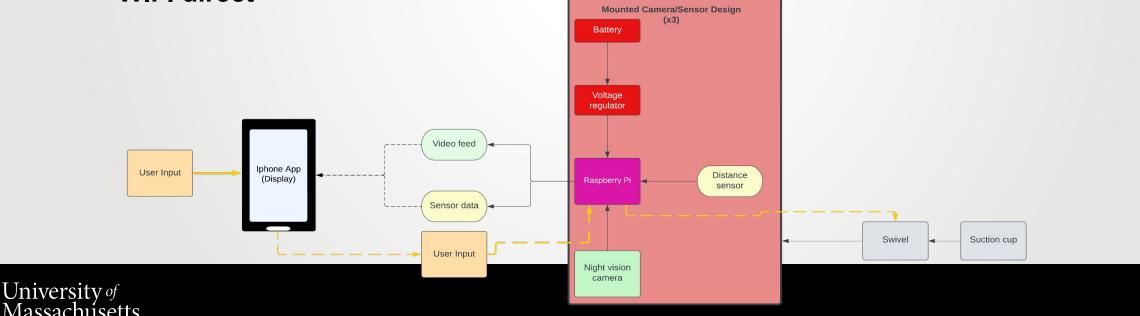




MDR Deliverables

Amherst

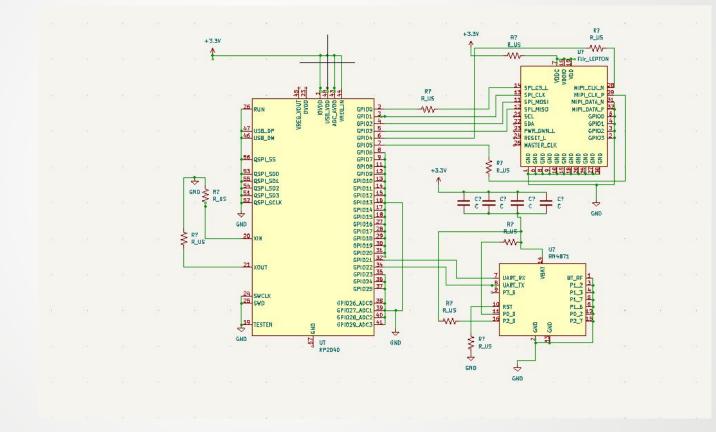
- Camera mounts can pan horizontally
- Cameras can be accessed and controlled through mobile app
- Cameras can switch to night vision mode
- Sensors provide correct data and communicate with the system successfully
- Microcontroller correctly taking in inputs and sending output to the user through WIFI direct



MDR PCB Deliverables

PCB Schematic

 Microcontroller, distance sensor and night vision camera PCB connection





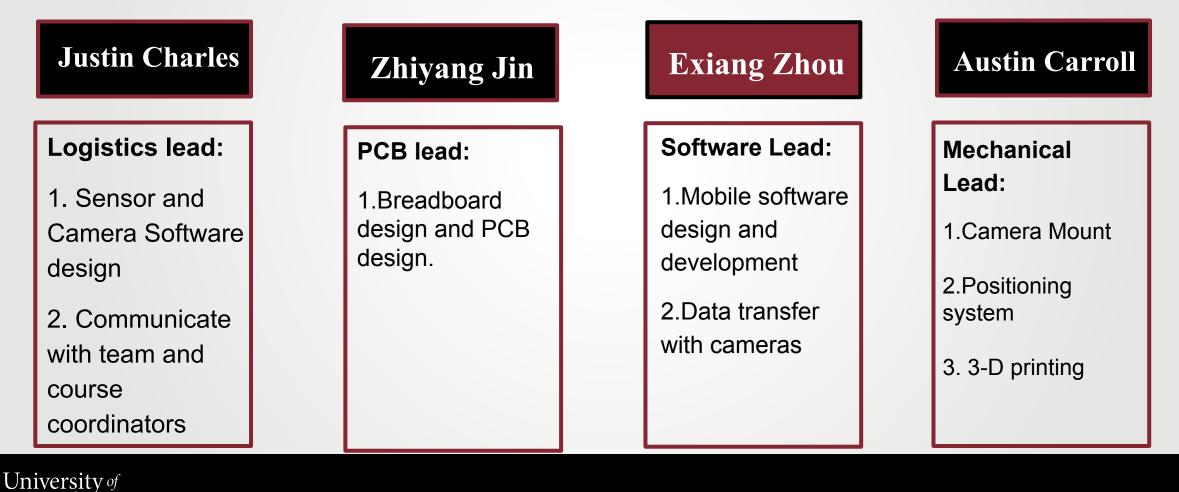
Parts List

- Raspberry Pi x3
- Lithium Battery
- HC-SR04 Distance Sensor x3
- Arducam Day&Night Vision Camera x3
- Suction Cup 4 Pack
- Custom PCBs
- A4988 Stepper Motor Driver Carrier x3
- Adafruit NFMA-17 12V 350 mA Stepper Motor x3
- 3D Printed Parts

- \$30
- \$18
- \$84
- \$20
- \$200
- \$15
- \$42
- \$0

Total: \$409

Team Roles



Gantt Chart

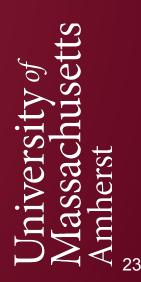
| | | | | Week 6 10/10 - 10/1 | 4 | | Week 7 /17 - 10/2 | 1 | 10034 | Week 8 10/24 - 10/28 | | | Week 9 10/31 - 11 | | | | | ek 10 - 11/* | | | | Week 11 /14 - 11/18 | | | | ek 12 - 11/2 | k 12 - 11/25 | | We | | |
|---|-------------------|---------------------|------|------------------------|----|-------------------------|----------------------|-------------------------|-------|-------------------------|------------------------|---|----------------------|------|-------------------------|---|---|-----------------|--------------------------|----|---|--------------------------|-----|---|---------|-----------------|------------------------|------------------------|-----------|-----|-----|
| Task | Team Member | Start Date - End Da | te N | 1 T W Th | FI | МТ | W Th | F | MT | W | Th F | М | ΤV | V Th | F | М | Т | W TI | n F | М | Т | W T | h F | M | Т | W TI | h F | М | T | W T | h F |
| Hardware | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Microcontroller connection to cameras and sensors | Justin C, Zhiyang | 10/13 - 10/21 | | | | | | | 3-17 | | | | | | | | | | | | | | | | | | | | | | |
| Mount and Rotation Mechanical design | Austin | 10/26 - 11/16 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Camera Casing Design | Austin | 11/15 - 11/28 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Breadboard Design | Zhiyang | 10/24 - 11/28 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | | | | Week 6 10/10 - 10/1 | 4 | Week 7 10/17 - 10/21 | | Week 8 10/24 - 10/28 | | | Week 9 10/31 - 11/4 | | | Ļ | Week 10 11/07 - 11/1 | | | | Week 11 11/14 - 11/18 | | | Week 12 11/21 - 11/25 | | | | | | Week 13 /28 - 12/02 | | | |
| Task | Team Member | Start Date - End Da | te N | I T W Th | FI | M T | W Th | F | M T | W | Th F | М | ΤV | V Th | F | М | Т | W TI | n F | M | Т | W T | h F | M | T | W TI | h F | Μ | T | W T | h F |
| Software | | | | | | | | | | | | | | | | | | | | 11 | · | | | | ter str | | | -1 | 11 | | |
| Camera software design | Justin C | 10/27 - 11/07 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Distance and software design | Justin C | 11/02 - 11/15 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Wireless data transfer | Justin L, Exiang | 10/18 - 11/23 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Mobile Phone Software Design | Exiang | 11/11 - 12/03 | | | | | | | 1 | | - 12 | | | | | | | | | | | | | | | | | | | | |
| Wireless Communication | Justin L | 10/13 - 10/27 | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |







Thank You!



Works Cited

Proximity Sensing:

- <u>https://ascencione.com/proximity-sensor-on-a-car-automobile/#:~:text=They%20are%20mounted%20on%20all.of</u> %20up%20to%2010%20feet
- <u>https://mycardoeswhat.org/safety-features/parking-sensors/</u>
- https://www.chevrolet.com/support/vehicle/driving-safety/parking/front-rear-park-assist

Back Up Camera Collision Decrease:

• <u>https://www.iihs.org/topics/bibliography/ref/2130</u>

Arducam Research

https://www.arducam.com/

Camera Panning system

https://www.youtube.com/watch?v=hEBjbSTLytk

Background Information

<u>https://www.rhoadsandrhoads.com/blog/avoid-an-accident-and-injuries-with-safer-towing-and-trailering/#:~:text=T he%20National%20Highway%20Traffic%20Safety,trailer%2C%20or%20an%20extra%20load</u>

Similar Solutions

- https://www.amazon.com/Wireless-Waterproof-License-Monitor-Trailer/dp/B0768TW5MW
- https://bulepods.com/product/1080p-hd-mini-wireless-mini-camera-camcorder-wifi-outdoor-home-security-dvr/?gcl

=Cj0KCQjw166aBhDEARIsAMEyZh6-ME4_35CjWQOa4GCF8a1MQw9MExEK2QYDPwgObFe4msGaK2f1U-Ya

AkMjEALw_wcB

- <u>https://www.tadibrothers.com/products/9-monitor-with-wireless-mounted-rv-backup-camera?gclid=Cj0KCQjw166a</u>
- <u>https://www.walmart.com/ip/WiFi-HD-Wireless-Car-Rear-View-Cam-Wireless-Backup-Camera-Waterproof-Camera-</u>

a-for-Cars-Trucks-Vans-Pickups-SUVs-WiFi-Backup/769954848?wmlspartner=wlpa&selectedSellerId=18988

